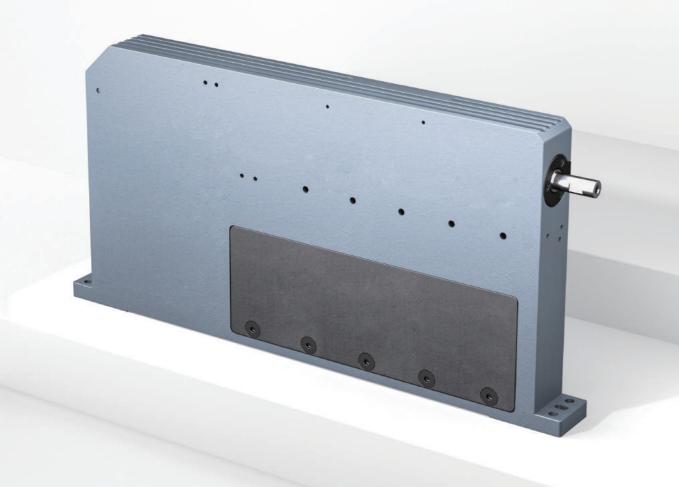
DLAR SERIES

Direct Drive Linear Rotary Actuator

DLAR-20-40(Optical/Magnetic encoder)

DLAR-25-50(Optical/Magnetic encoder)



PRODUCT FEATURES

High performance Linear/Rotary motion Adjustable parameters

Provide accurate linear and rotary actions of the Z-axis during high-speed motion, with adjustable velocity, thrust, and position parameters, enabling complex actions requiring high frequency and high precision.

Hollow rod Soft landing **Power-off protection**

The product is compact, light, and thin. It employs a hollow rod design to support pick-and-place tasks. The intelligent soft landing function protects the picked and placed workpiece with precise force control. The Z-axis has a built-in spring to prevent the axis from falling off due to power-off during vertical operations.

Precision resolution Long life over 100 million cycles

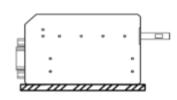
Regarding this product, the stroke resolution is up to 0.5 μ m, the rotary position resolution is 0.005°. With high-quality guide rail-level related components, it has a service life of up to 100 million cycles, and it is stable and durable.

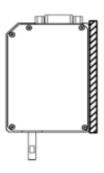
INSTALLATION METHOD

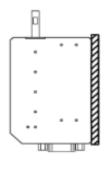
Install it using the screw holes on the back of the product.

Installation directions:

- Horizontal direction
- Vertical installation with the vertical rod pointing down
- Vertical installation with the vertical rod pointing up



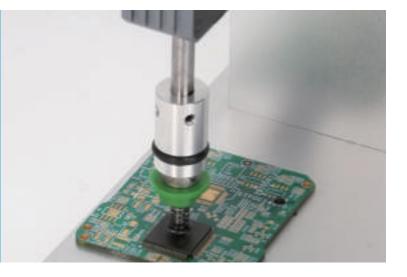




APPLICATION SCENARIOS

The force repeatability of ± 3 g and the micron-level resolution can be applied to the fast pick-and-place, assembly, testing, and other scenarios in semiconductors, 3C electronics, and other industries.

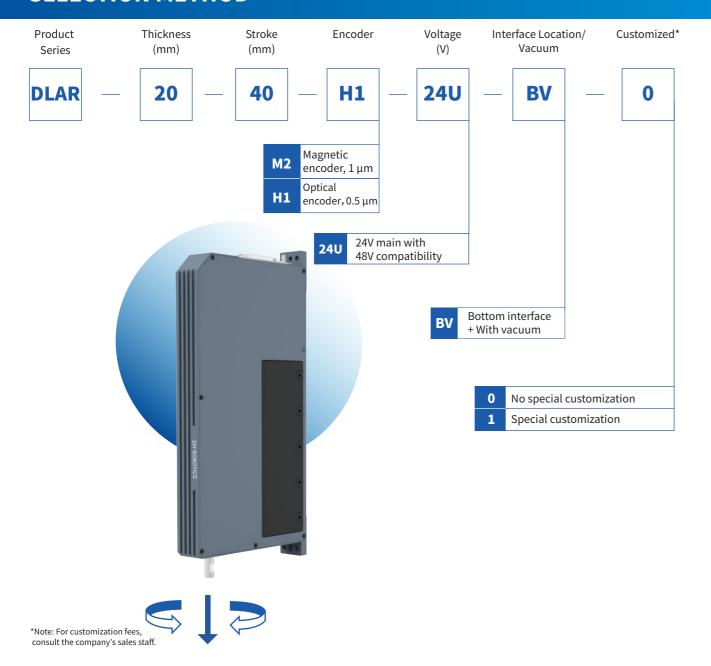
The unique linear and rotary motions of the Z-axis of the VLAR series can adapt to more abundant industrial scenarios, such as positioning, correction, and assembly in medical automation, 3C, and packaging automation.



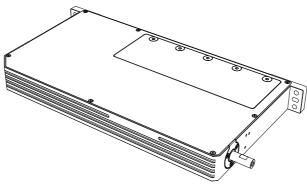
DLAR-20-40 (Optical/Magnetic encoder)

DIRECT DRIVE LINEAR ROTARY ACTUATOR

SELECTION METHOD



TECHNICAL SPECIFICATIONS









For specific selection of voice coil products, please contact DH-Robotics or authorized agent for application and process confirmation.
When higher requirements for actuators are required, please contact engineering staff.

Performance specifications					
Peak thrust	33	N			
Continuous thrust	11	. N			
Total stroke	40 r	mm			
Force repeatability	±5 g				
Force constant	9.2 N/A				
Maximum torque	0.056	$N \cdot m$			
Maximum speed	2000 rpm				
Linear stroke resolution	$1\mu m^{\text{(Magnetic grid}\atop encoder)}$	$0.5~\mu m$ (Optical encoder)			
Positioning repeatability	$\pm 5\mu m^{\text{(Magnetic grid}\atop encoder)}$	$\pm 2\mu m_{{}_{encoder)}}^{{}_{(Optical}}$			
Rotary encoder resolution	0.02° (Magnetic grid encoder)	0.005° (Optical encoder)			
Mechanical specific	ations				
Overall mass	1100 g				
Mayable part mass	Mayahla namburana				

rectianted specifications		
Overall mass	1100 g	
Movable part mass	180 g	
Size	195 mm x 106 mm x 20 m	

Size	195 mm x 106 mm x 20 m
Vacuum	With vacuum

Operating voltage	24 V DC \pm 10%
Continuous current	(Linear)1.2 A (Rotary)0.6 A
Peak current	(Linear)3.5 A (Rotary)2.5 A
Recommended load	≤150 g
Recommended load inertia	20 g·cm ²
IP rating	IP 40
Recommended operating	0°C-40°C. 85% RH or less

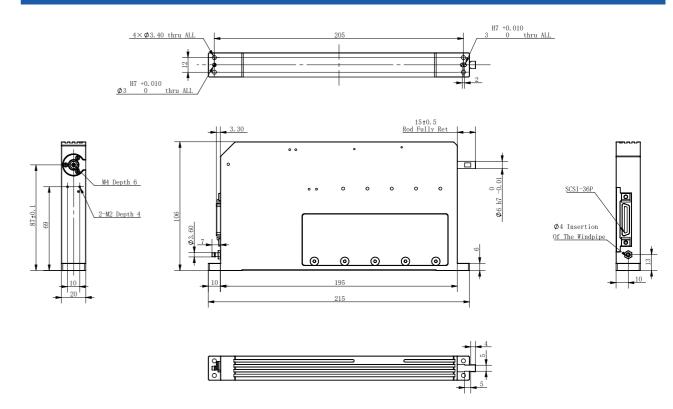
environmen International standard

Operating environment

CE, FCC, RoHS compliance

Dimensions

Intelligent



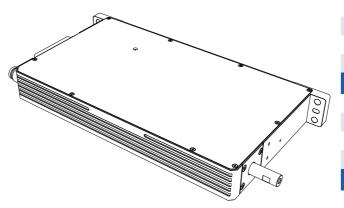
DLAR-25-50 (Optical/Magnetic encoder)

DIRECT DRIVE LINEAR ROTARY ACTUATOR

SELECTION METHOD



TECHNICAL SPECIFICATIONS









For specific selection of voice coil products, please contact DH-Robotics or authorized agent for application and process confirmation.
When higher requirements for actuators are required, please contact engineering staff.

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	Performance specifications					
	Peak thrust	26	N			
	Continuous thrust	81	8 N			
	Total stroke	50 n	50 mm			
	Force repeatability	±10	±10 g			
	Force constant	6.6 N	6.6 N/A			
	Maximum torque	1 80.0	0.03 N·m			
	Maximum speed	800 r	800 rpm			
	Linear stroke resolution	1 μm (Magnetic grid encoder)	$0.5~\mu m~_{\text{encoder})}^{\text{(Optical}}$			
	Positioning repeatability	$\pm 5\mu m^{\text{(Magnetic grid}\atop encoder)}$	$\pm 2\mu m_{{}_{encoder)}}^{{}_{(Optical}}$			
	Closed-loop stepper motor with encoder resolution	2000	2000 lines			
	Mechanical specific	ations				
	Overall mass	1170 g				
	Movable part mass	245 g				
	Size	200 mm x 115 mm x 25 mm				
	Vacuum	With va	With vacuum			
	Operating environn	nent				
	Operating voltage	24 V DC	24 V DC ± 10%			
	Continuous current		(Linear)1.2 A (Rotary)0.8 A			
	Peak current	(Linear)4.0 A (Rotary)1.2 A				
	Recommended load	150	150 g			
	Recommended load inertia	a 20 g·	20 g⋅cm²			
	IP rating	IP 4	IP 40			
	Recommended operating environmen	0°C-40°C, 85°	0°C-40°C, 85% RH or less			
	International standard compliance	CE, FCC	CE, FCC, RoHS			

Dimensions

